COM521500 Math. Methods for SP I Lecture 2: Eigenvalues and Eigenvectors

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Lecture 2: Eigenvalues and Eigenvectors

The Basics

Let A be an $n \times n$ matrix. The eigenvalue problem is to find a vector v such that

$$Av = \lambda v, v \neq 0$$

The scalar λ is called an **eigenvalue** of **A**, and the vector **v** is called an **eigenvector** of **A**.

The eigen-equation can be rewritten as

$$(\mathbf{A} - \lambda \mathbf{I})\mathbf{v} = \mathbf{0},$$

which is satisfied if and only if $\mathbf{A} - \lambda \mathbf{I}$ is singular. Thus,

$$\det(\mathbf{A} - \lambda \mathbf{I}) = 0 \tag{(*)}$$

Eq. (*) is called the characteristic equation of A, and $det(A - \lambda I)$ is called the characteristic polynomial of A.

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The function $det(\mathbf{A} - \lambda \mathbf{I})$ is a polynomial of degree n, which means that it can be factored as

$$\det(\mathbf{A} - \lambda \mathbf{I}) = \prod_{i=1}^{n} (\lambda_i - \lambda)$$

where $\lambda_1, \ldots, \lambda_n$ are the roots of the polynomial.

Thus,

$$\mathbf{A}\mathbf{v}_i = \lambda_i \mathbf{v}_i, \quad i = 1, \dots, n$$

where \mathbf{v}_i is the eigenvector associated with the eigenvalue λ_i , for i = 1, ..., n.

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Some remarks:

- For any eigenvector v_i, any vector cv, c ∈ ℝ is also an eigenvector. Often, the eigenvectors are assumed to be normalized; i.e., ||v_i||₂ = 1.
- 2. For an $\mathbf{A} \in \mathbb{R}^{n \times n}$, it is possible to have complex-valued λ_i 's (recall a root of a real-valued polynomial can be complex-valued). Under such circumstances the eigenvectors may be complex-valued too. Hence, it is convenient for us to study the case of $\mathbf{A} \in \mathbb{C}^{n \times n}$, which subsumes the case of $\mathbf{A} \in \mathbb{R}^{n \times n}$.

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Similarity, and Diagonalizability

A matrix $\mathbf{B} \in \mathbb{C}^{n \times n}$ is similar to a matrix $\mathbf{A} \in \mathbb{C}^{n \times n}$ if there exists a nonsingular matrix $\mathbf{S} \in \mathbb{C}^{n \times n}$ such that

$$\mathbf{B} = \mathbf{S}^{-1} \mathbf{A} \mathbf{S}$$

Property 2.1 If A and B are similar, then the characteristic polynomial of A is same as that of B.

Property 2.2 If A and B are similar, then they have the same eigenvalues, and the same determinant.

A matrix $\mathbf{A} \in \mathbb{C}^{n \times n}$ is said to be **diagonalizable** if it is similar to a diagonal matrix.

In other words, for a diagonalizable matrix ${\bf A}$ we can find a nonsingular matrix ${\bf S}$ such that

$$\mathbf{A} = \mathbf{S}\mathbf{D}\mathbf{S}^{-1}$$

where \mathbf{D} is a diagonal matrix.

Theorem 2.1 A matrix $\mathbf{A} \in \mathbb{C}^{n \times n}$ is diagonalizable if and only if there is a set of n linearly independent vectors, each of which is an eigenvector of \mathbf{A} .

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Distinct eigenvalues

Property 2.3 Suppose that $\{\lambda_1, \ldots, \lambda_k\}$, $k \leq n$, is a set of distinct eigenvalues; i.e, $\lambda_i \neq \lambda_j$ for $i \neq j$, $i, j \in \{1, 2, \ldots, k\}$. Then, the corresponding set of eigenvectors $\{\mathbf{v}_1, \ldots, \mathbf{v}_k\}$ is linearly independent.

It follows that if all the eigenvalues of A are distinct, then A is diagonalizable.

Repeated eigenvalues

In the case where there are, say, r repeated eigenvalues, then a linearly independent set of r eigenvectors for those eigenvalues exists, provided that

$$\operatorname{rank}(\mathbf{A} - \lambda \mathbf{I}) = n - r \tag{(*)}$$

Example: Show that

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

satisfies Condition (*).

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Assume that the eigenvectors of A are linear independent. From Theorem 2.1, we obtain the following eq. known as the **eigendecomposition**:

$$\mathbf{A} = \mathbf{V} \mathbf{\Lambda} \mathbf{V}^{-1}$$

where

$$\mathbf{V} = \begin{bmatrix} \mathbf{v}_1, \dots, \mathbf{v}_n \end{bmatrix}$$
$$\mathbf{\Lambda} = \text{Diag}(\lambda_1, \dots, \lambda_n) = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & & \lambda_n \end{bmatrix}$$

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Orthogonality

Two vectors \mathbf{x}, \mathbf{y} (either real or complex valued) are said to be **orthogonal** if

$$\langle \mathbf{x}, \mathbf{y} \rangle = 0$$

A set of vectors $\{\mathbf{x}_1, \dots, \mathbf{x}_m\}$ is said to be **orthogonal** if $\langle \mathbf{x}_i, \mathbf{x}_k \rangle = 0$ for all $i \neq k$.

A set of vectors $\{\mathbf{x}_1, \dots, \mathbf{x}_m\}$ is said to be **orthonormal** if $\langle \mathbf{x}_i, \mathbf{x}_k \rangle = 0$ for all $i \neq k$, and $\|\mathbf{x}_i\|_2^2 = 1$ for all i.

Property: An orthogonal set of vectors is linearly independent.

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A matrix $\mathbf{U} \in \mathbb{C}^{n \times n}$ is said to be **unitary** if

$$\mathbf{U}^{H}\mathbf{U} = \mathbf{I}$$

A matrix $\mathbf{U} \in \mathbb{R}^{n \times n}$ is said to be **orthogonal** if

$$\mathbf{U}^T\mathbf{U} = \mathbf{I}$$

From the definition, a unitary (orthogonal) matrix is a matrix where its columns form an orthonormal set of vectors.

Some properties for unitary (orthogonal) matrices:

- 1. $\mathbf{U}^{-1} = \mathbf{U}^H.$
- 2. $\mathbf{U}\mathbf{U}^H = \mathbf{I}$.
- 3. The rows of ${\bf U}$ form an orthonormal set of vectors.

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Symmetric and Hermitian matrices

A matrix $\mathbf{A} \in \mathbb{R}^{n imes n}$ is symmetric when

$$\mathbf{A} = \mathbf{A}^{T}$$

A matrix $\mathbf{A} \in \mathbb{C}^{n \times n}$ is **Hermitian** when

$$\mathbf{A} = \mathbf{A}^{H}$$

A real sym. matrix is a Hermitian matrix.

Note: Symmetric and Hermitian matrices are very frequently encountered in SP, and hence their eigenvector/ eigenvalue properties deserve particular attention.

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Property 2.4 The eigenvalues of a Hermitian matrix are real.

Property 2.5 Let A be a Hermitian matrix, and suppose that all the eigenvalues of A are distinct. Then, the eigenvectors of A are mutually orthogonal.

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We conclude that under the distinct eigenvalue assumption, the eigendecomposition of a Hermitian ${\bf A}$ is

$$\mathbf{A} = \mathbf{V} \mathbf{\Lambda} \mathbf{V}^H$$
 ($\mathbf{A} = \mathbf{V} \mathbf{\Lambda} \mathbf{V}^T$ for real sym. \mathbf{A})

Now the question remained is: can a Hermitian (real sym.) matrix have eigendecomposition?

This question has been answered by **Schur triangular**ization theorem.

Theorem 2.2 (Schur triangularization) Given a matrix $\mathbf{A} \in \mathbb{C}^{n \times n}$, there exists a unitary matrix $\mathbf{U} \in \mathbb{C}^{n \times n}$ such that

$$\mathbf{U}^H \mathbf{A} \mathbf{U} = \mathbf{T}$$

where T is an upper triangular matrix with main diagonal $\operatorname{diag}(\mathbf{T}) = [\lambda_1, \dots, \lambda_n]^T.$

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Now, consider a Hermitian A.

$$\mathbf{T}^{H} = (\mathbf{U}^{H}\mathbf{A}\mathbf{U})^{H}$$
$$= \mathbf{U}^{H}\mathbf{A}^{H}\mathbf{U} = \mathbf{U}^{H}\mathbf{A}\mathbf{U} = \mathbf{T}$$

This implies that T is diagonal, and that $T = \Lambda$. Thus,

Theorem 2.3 A Hermitian matrix $\mathbf{A} \in \mathbb{C}^{n \times n}$ can always be diagonalized as

$$\mathbf{V}^{H}\mathbf{A}\mathbf{V} = \mathbf{\Lambda}$$
 ($\mathbf{V}^{T}\mathbf{A}\mathbf{V} = \mathbf{\Lambda}$ for real sym. \mathbf{A})

where $\Lambda = [\lambda_1, \ldots, \lambda_n]$, $\mathbf{V} = [\mathbf{v}_1, \ldots, \mathbf{v}_n]$, $\{\lambda_i\}$ is the set of eigenvalues of \mathbf{A} , \mathbf{v}_i is the normalized eigenvector of \mathbf{A} associated with λ_i .

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Some properties obtained from Theorem 2.3:

Property 2.6 For Hermitian A, $\mathbf{A}^{-1} = \mathbf{V} \mathbf{\Lambda}^{-1} \mathbf{V}^{H}$. [note that $\mathbf{\Lambda}^{-1} = \text{Diag}(\frac{1}{\lambda_{1}}, \dots, \frac{1}{\lambda_{n}})$.]

Property 2.7 For Hermitian A, rank(A) is the number of nonzero eigenvalues.

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Matrix Norms

The definition of a matrix norm is equivalent to that of a vector norm.

Specifically, a matrix norm is a function $\|.\| : \mathbb{C}^{m \times n} \to \mathbb{R}$ that satisfies the following properties:

- 1. $\|\mathbf{X}\| \ge 0$ for all $\mathbf{X} \in \mathbb{C}^{m \times n}$
- 2. $\|\mathbf{X}\| = 0$ if and only if $\mathbf{X} = \mathbf{0}$
- 3. $\|\mathbf{X} + \mathbf{Y}\| \le \|\mathbf{X}\| + \|\mathbf{Y}\|$ for any $\mathbf{X}, \mathbf{Y} \in \mathbb{C}^{m \times n}$
- 4. $\|c\mathbf{X}\| = |c|\|\mathbf{X}\|$ for $c \in \mathbb{C}$, $\mathbf{X} \in \mathbb{C}^{m \times n}$

Frobenius Norm:

$$\|\mathbf{A}\|_F^2 = \left[\sum_{i=1}^m \sum_{k=1}^n |a_{ik}|^2\right]^{1/2}$$

Note that

$$\|\mathbf{A}\|_F^2 = \left[\operatorname{tr}(\mathbf{A}^H \mathbf{A})\right]^{1/2}$$

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Matrix *p*-Norms:

$$\begin{aligned} \|\mathbf{A}\|_p^2 &= \sup_{\mathbf{x}\neq\mathbf{0}} \frac{\|\mathbf{A}\mathbf{x}\|_p}{\|\mathbf{x}\|_p} \\ &= \max_{\|\mathbf{x}\|_p=1} \|\mathbf{A}\mathbf{x}\|_p \end{aligned}$$

For the matrix 2-norm,

$$\|\mathbf{A}\|_2 = \sqrt{\lambda_{max}}$$

where λ_{max} is the largest eigenvalue of $\mathbf{A}^{H}\mathbf{A}$.

As we will see later in this course, $\|\mathbf{A}\|_2$ is also the largest singular value of \mathbf{A} .

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Some useful inequalities:

- 1. $\|\mathbf{A}\mathbf{x}\|_p \leq \|\mathbf{A}\|_p \|\mathbf{x}\|_p$
- 2. Let ${\bf Q}$ and ${\bf Z}$ be unitary matrices of appropriate sizes.

$$\|\mathbf{Q}\mathbf{A}\mathbf{Z}\|_2 = \|\mathbf{A}\|_2$$
$$\|\mathbf{Q}\mathbf{A}\mathbf{Z}\|_F = \|\mathbf{A}\|_F$$

3. $\|\mathbf{AB}\|_p \leq \|\mathbf{A}\|_p \|\mathbf{B}\|_p$

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